HINES CONTROL MORE PROTECTION	Eastin mant.	FIXTURE																
BAJAJ Distinctly Ahead	Equipment :		ļ	Defect		_						_						
	Department	FIX MAINTANANCE		Result :	N	Р		Q	С	D	S			KAIZEN IDEA SHEET				
				Type :	<u> </u>													
Cell: RO	OBOTIC LINE				Ope	ration :	:	Z spoti	ng fixtu	ıre								
Kaizen Theme: Co	opper plate life increa	sed		milling frequency increased & copper plate position shift														
Problem / Present Status			Counter Measure					Ben	chmar	k:								
High copper plate milling frequency 8 to 10 days			Copper plate milling frequency increased-15 to 20 days					Tar	Target: 30 D.					DAYS				
								Sta	rt:	0	2/04/201	4		Finished :	(08/04/20	14	
	9 9							Not	e :									
	8							Tea	m Men	nbers	:							
	d CO	3-0						1. N	1. MR S.B. RATHOD					2. MR D.G KADAM				
								3. N	3. MR HARI					4. MR SAVRAV				
	10/			45	2.50			5.						6.				
	1 de	-	2	1°L				Ben	efits					-				
=	-	17/11/2	2 1	100	T	100.0		С	1) Elir	ninated	d copper p	plate o	consump	tion Rs 0.00	0			
	1							C Save Cost of Rs per plate 2500/-2 month Rs 0.00										
=		W. T. W. T.							Q Quality spot improve Rs 0.00									
Mby Mby Analysis			Result:							_4								
Why Why Analysis :								_	zen Su									
W1 : W1: Robotic spott	ing during at one place	ce	Copper plate life increased by 50 %					_			int Added	in JH	I check s	heet.				
W1 : W1: Robotic spotti		ce						_				in JH	I check s	heet.				
W1 : W1: Robotic spotti A1 : W2 : W2: Copper plate		ce						Wha	at To D	o : Poi				heet.				
W1 : W1: Robotic spotti A1 : W2 : W2: Copper plate A2 :		ce						Wha	at To D	o : Poi	int Added			heet.				
W1: W1: Robotic spotti A1: W2: W2: Copper plate A2: W3:		ce						Wha	at To D	o:Poi	int Added			heet.				
W1: W1: Robotic spotti A1: W2: W2: Copper plate A2: W3:		ce						Wha	at To D	o:Poi	int Added			heet.				
W1: W1: Robotic spotti A1: W2: W2: Copper plate A2: W3: A3:		ce						What Hov	at To Do	o: Poi	int Added	nly pm	ı plan	heet.				
W1: W1: Robotic spotti A1: W2: W2: Copper plate A2: W3:		ce						What Hov	v To Do	o: Poi	oer month	nly pm	ı plan			Tota	I	
W1: W1: Robotic spotti A1: W2: W2: Copper plate A2: W3: A3:		ce						What Hov	v To Do quency tincui	o: Poi	oer month	nly pm	plan	r Cost		Tota 0.00		
W1: W1: Robotic spotti A1: W2: W2: Copper plate A2: W3: A3:		ce						Hov Free Cos	v To Do	o: Poi	oer month	g Kaiz	zen : Labou	r Cost				
W1: W1: Robotic spotti A1: W2: W2: Copper plate A2: W3: A3: W4:		ce						Hov Free Cos	v To Do	o: Poi	oer month	g Kaiz	zen : Labou	r Cost	Targe	0.00		
W1: W1: Robotic spotti A1: W2: W2: Copper plate A2: W3: A3:		ce						Hov Free Cos	v To Do	o: Poi	or Making	g Kaiz	zen : Labou	r Cost	Targe	0.00)	
W1: W1: Robotic spotti A1: W2: W2: Copper plate A2: W3: A3: W4: A4:	position shift	ce						Hov Free Cos	v To Do	o: Poi	or Making	g Kaiz	zen : Labou	r Cost	Targe	0.00)	
W1: W1: Robotic spotti A1: W2: W2: Copper plate A2: W3: A3: W4: A4:	position shift	ce						Hov Free Cos	v To Do	o: Poi	or Making	g Kaiz	zen : Labou	r Cost	Targe	0.00)	
W1: W1: Robotic spotti A1: W2: W2: Copper plate A2: W3: A3: W4: A4: Root Cause Date: 10 Registered By: Mi	position shift 0/04/2014 r. Amol Dadpe	ce						Hov Free Cos	at To Do v To Do quency st Incur Mate	o: Poi	or Making	g Kaiz	zen : Labou	r Cost	Targe	0.00)	
W1: W1: Robotic spotti A1: W2: W2: Copper plate A2: W3: A3: W4: A4:	position shift 0/04/2014 r. Amol Dadpe r. S.R.Phatale	ce						Hov Free Cos	at To Do v To Do quency st Incur Mate	o: Poi	or Making	g Kaiz	zen : Labou	r Cost	Targe	0.00)	